## ROBOTICS ENGINEERING (BS) / ROBOTICS ENGINEERING (MS) (COMBINED OPTION)

## Program Overview

## BS Overview

Robotics Engineering degree is a four-year course of study leading to exciting careers and/or advanced studies in robotics and automation. The robotics engineering faculty are dedicated to undergraduate and graduate teaching and to working closely with students at all levels of their study. The program equips students with the practical skills of an engineer combined with the fundamental knowledge and understanding gained through the study of physics. The program allows for a focus on the hardware, modeling and programming all of which are the integral components of robotics.

The application of robotics is a "multi-craft" activity in that it is the blending of multiple disciplines including computer engineering, mechanical engineering, and electrical engineering. A roboticist engages in the design, construction, and programming of robotic systems, including wheeled mobile robots, drones (unmanned aerial systems), autonomous marine vehicles, space systems, and industrial robot manipulators.

## Career Opportunities

Students graduating with a Bachelor's degree in Robotics Engineering typically work in the robotics and automation industry or continue their studies in graduate school, or enter the armed services.

## MS Overview

Master of Science degree in Robotics Engineering offers a comprehensive course of study in robotics. Research opportunities exist for students to actively participate in the program's research activities.
The research areas include image processing, computer vision, artificial intelligence, industrial robot manipulators, unmanned aerial vehicles, autonomous ground robots, embedded systems, and microelectronics.

## Career Opportunities

Robotics Engineering graduates typically work in the robotics industry, continue their studies in doctoral programs at premier institutions.

## Program of Study

| Code | Title | Credit <br> Hours |
| :--- | :--- | ---: |
| Core IMPACTS Area : Institutional Priorities | 1 | $\mathbf{4 - 5}$ |
| COMM 1110 | Public Speaking | 3 |
| ITDS 1779 | Scholarship Across the Disciplines | 2 |
| LEAD 1705 | Introduction to Servant Leadership | 2 |
| PERS 1506 | Perspectives 1-hour | 1 |
| PERS 1507 | Perspectives 2-hour | 2 |

Foreign Language Course Options

| ARAB, CHIN, FREN, GERM, GREK, ITAL, JAPN, KREN, LATIN, PORT, SPAN - 1001, 1002, 2001, 2002 |  |  |
| :---: | :---: | :---: |
| SWAH 1001 | Elementary Swahili I |  |
| SWAH 1002 | Elementary Swahili II |  |
| Core IMPACTS Area : Mathematics \& Quantitative Skills ${ }^{1}$ |  | 3-7 |
| DATA 1501 | Introduction to Data Science | 3 |
| MATH 1001 | Quantitative Skills and Reasoning | 3 |
| MATH 1101 | Introduction to Mathematical Modeling | 3 |
| MATH 1111 | College Algebra | 3 |
| MATH 1113 | Pre-Calculus | 4 |
| MATH 1125 | Applied Calculus | 3 |
| MATH 1131 | Calculus with Analytic Geometry I | 4 |
| MATH 1132 | Calculus with Analytic Geometry II | 4 |
| MATH 1165 | Computer-Assisted Problem Solving | 3 |
| MATH 1401 | Introduction to Statistics | 3 |
| MATH 1501 | Calculus I | 4 |
| MATH 2125 | Introduction to Discrete Mathematics | 3 |
| STAT 1401 | Elementary Statistics | 3 |
| Core IMPACTS Area : Political Science and U.S. History |  | 6 |
| HIST 2111 | U. S. History to 1865 | 3 |
| or HIST 2112 | U. S. History since 1865 |  |
| POLS 1101 | American Government | 3 |
| Core IMPACTS Area : Arts, Humanities, and Ethics |  | 6 |
| Select one Fine Arts course |  | 3 |
| ARTH 1100 | Art Appreciation |  |
| ARTH 2125 | Introduction to the History of Art I- Prehistoric through Gothic |  |
| ARTH 2126 | Introduction to the History of Art II- Renaissance through Modern |  |
| MUSC 1100 | Music Appreciation |  |
| THEA 1100 | Theatre Appreciation |  |
| ITDS 1145 | Comparative Arts ${ }^{2}$ |  |
| Select one Humanities course |  | 3 |
| ENGL 2111 | World Literature I |  |
| ENGL 2112 | World Literature II |  |
| ITDS 1774 | Introduction to Digital Humanities |  |
| PHIL 2010 | Introduction to Philosophy |  |
| ITDS 1145 | Comparative Arts ${ }^{2}$ |  |
| Core IMPACTS Area : Communicating in Writing |  | 6 |
| ENGL 1101 | English Composition I | 3 |
| ENGL 1102 | English Composition II | 3 |
| Core IMPACTS Area : Technology, Mathematics, and Sciences ${ }^{1}$ |  | 7-11 |
| ANTH 1145 | Human Origins | 3 |
| ASTR 1105 | Descriptive Astronomy: The Solar System | 3 |
| ASTR 1106 | Descriptive Astronomy: Stars and Galaxies | 3 |
| ASTR 1305 | Descriptive Astronomy Lab | 1 |
| ATSC 1112 | Understanding the Weather | 3 |
| ATSC 1112L | Understanding the Weather Lab | 1 |
| BIOL 1125 | Contemporary Issues in Biology Non-Lab | 3 |
| BIOL 1215K | Introductory Biology | 4 |
| BIOL 1225K | Contemporary Issues in Biology with Lab | 4 |
| CHEM 1151 <br> \& 1151L | Survey of Chemistry I and Survey of Chemistry I Lab | 4 |



Select one PEDS course (https://catalog.columbusstate.edu/coursedescriptions/peds/\#peds)

1 The hours applied in the Institutional Priorities; Mathematics \& Quantitative Skills; and Technology, Mathematics, and Sciences areas must add to 18 credit hours.
2 ITDS 1145 Comparative Arts, though listed under both Fine Arts and Humanities, may be taken only once.

## Major Requirements



Field of Study Requirements Total
18

## Required for the Major

Minimum grade of C is required
ENGR 1701 Introduction to Robotics 1
ENGR 2115 Statics 3
ENGR 2125 Dynamics of Rigid Bodies 3
ENGR 2206 Digital Logic 4
ENGR 3235 Circuit Analysis 3
ENGR 3236 Introduction to Signal Processing 3
ENGR 3245 Robotics Engineering Design Lab 2
ENGR 3255 Sensors and Actuators 3

ENGR 3275 Feedback Control Systems 3
ENGR 4391 Robotics Senior Design 12
ENGR 4392 Robotics Senior Design 2
ENGR 5151 G Computer Vision 1 (Also applies toward the 3 master's degree requirements)
ENGR 5161U Elements of Machine Intelligence 3
ENGR 5176U Kinematics and Dynamics 3
ENGR 5236G Microelectronic Circuits (Also applies toward the 3 master's degree requirements)
ENGR 5238G Introduction to Embedded Systems (Also applies 3
toward the master's degree requirements)
MATH 3107 Differential Equations 3
MATH 3175 Introduction to Probability 3
Required for the Major Total 50
Major Electives
Include 1 hour from MATH 1132 in Area D 1
Choose 9 hours from the following options: 9
Any 1000+ science course

Any 1000+ ENGR course
Any $2000+$ MATH/STAT class with advisor approval
Any $3000+$ CPSC class with advisor approval
Area H Total

## Master's Degree Requirements

## Area 1

The following 3 courses are taken with the bachelor's degree but also count toward the master's degree requirements.

| ENGR 5151G | Computer Vision 1 |
| :--- | :--- |
| ENGR 5236G | Microelectronic Circuits |
| ENGR 5238G | Introduction to Embedded Systems |
| Take four additional courses from the following list to accumulate an | 12 |
| additional 12 credit hours in Area 1: |  |
| ENGR 6137 | Dynamic Optimization |
| ENGR 6145 | Human-Robot Interactions |
| ENGR 6148 | Military Applications in Robotics |
| ENGR 6152 | Computer Vision 2 |
| ENGR 6162 | Machine Intelligence and Synthesis |
| ENGR 6167 | Multi-Robot Systems |
| ENGR 6172 | Multivariable Linear Controls |
| ENGR 6173 | Nonlinear Controls |
| ENGR 6178 | Biomechanics |
| ENGR 6239 | Embedded Systems Design |
| ENGR 6555 | Selected Topics in Robotics |
| Any 5000+ CPSC/MATH class with advisor approval |  |
| Area 1 Total |  |

## Area 2

Choose one of the following 2 options for 9 additional credit hours 9
Thesis Option
ENGR 6000 Thesis Defense
ENGR 6999 Thesis Research (Repeat to complete a total of 9 hours)

## Nonthesis Option

Take one of the following two courses twice for a total of 6 hours
ENGR 6399 Graduate Research Project
ENGR 6689 Supervised Graduate Internship
Choose one of the following courses that is not applied in Area 1:

| ENGR 6137 | Dynamic Optimization |
| :--- | :--- |
| ENGR 6145 | Human-Robot Interactions |
| ENGR 6148 | Military Applications in Robotics |
| ENGR 6152 | Computer Vision 2 |
| ENGR 6162 | Machine Intelligence and Synthesis |
| ENGR 6167 | Multi-Robot Systems |
| ENGR 6172 | Multivariable Linear Controls |
| ENGR 6173 | Nonlinear Controls |
| ENGR 6178 | Biomechanics |
| ENGR 6239 | Embedded Systems Design |
| ENGR 6555 | Selected Topics in Robotics |
| Any 5000+ CPSC/MATH class with advisor approval |  |
| Area 2 Total |  |

Total Credit Hours ..... 144

## Program Map BS/MS Robotics Engineering Non-Thesis Option 1

| Course | Title | Credit |
| :--- | :--- | :--- |
|  | Hours |  |

## First Year

Fall

| ENGL 1101 | English Composition I (minimum grade of C) | 3 |
| :---: | :---: | :---: |
| MATH 1131 | Calculus with Analytic Geometry I (minimum grade of C ) | 4 |
| CHEM 1211 | Principles of Chemistry I (minimum grade of C) | 3 |
| CHEM 1211L | Principles of Chemistry I Lab (minimum grade of C) | 1 |
| ENGR 1701 | Introduction to Robotics (minimum grade of C) | 1 |
| ENGR 2255 | Engineering Graphics and Computer Aided Design (minimum grade of C) | 3 |
| Area B2 | Institutional Options Elective ${ }^{1}$ | 1 |
|  | Credit Hours | 16 |
| Spring |  |  |
| ENGL 1102 | English Composition II (minimum grade of C) | 3 |
| MATH 1132 | Calculus with Analytic Geometry II (minimum grade of C) | 4 |
| PHYS 2211 | Principles of Physics I (minimum grade of C) | 3 |
| PHYS 2311 | Principles of Physics I Lab (minimum grade of C) | 1 |
| Area H | Elective (minimum grade of C) ${ }^{2}$ | 3 |
| KINS 1106 or PHED 1205 | Lifetime Wellness or Concepts of Fitness | 2 |
|  | Credit Hours | 16 |

## Second Year

Fall

| MATH 2115 | Introduction to Linear Algebra (minimum <br> grade of C) | 3 |
| :--- | :--- | ---: |
| PHYS 2212 | Principles of Physics II (minimum grade of <br> C) | 3 |
| PHYS 2312 | Principles of Physics II Lab (minimum <br> grade of C) | 1 |
| ENGR 2115 | Statics (minimum grade of C) | 3 |
| ENGR 2221 | Computing for Engineers 1 (minimum <br> grade of C) | 3 |
| Area E | Behavioral Science Elective ${ }^{3}$ | 3 |
|  | Credit Hours | $\mathbf{1 6}$ |

## Spring

MATH 3107 Differential Equations (minimum grade of 3 C)
ENGR 2206 Digital Logic (minimum grade of C) 4
ENGR 2125 Dynamics of Rigid Bodies (minimum grade 3 of C)
Area $\mathrm{H} \quad$ Elective $(\text { minimum grade of } \mathrm{C})^{2} 3$

| Area B1 | Institutional Options Elective ${ }^{4}$ | 3 | ENGR 6399 | Graduate Research Project | 3 |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | Credit Hours | 16 |  | Credit Hours | 12 |
| Third Year |  |  |  | Total Credit Hours | 147 |
| Fall |  |  |  |  |  |
| MATH 2135 | Calculus with Analytic Geometry 3 (minimum grade of C) | 4 | Footnotes |  |  |
| ENGR 3235 | Circuit Analysis (minimum grade of C) | 3 | Area B2: ITDS 1779 (2) or LEAD 1705 (2) or PERS 1506 (1; may be repeated with different topic) or PERS 1507 (2). |  |  |
| ENGR 3236 | Introduction to Signal Processing (minimum grade of C ) | 3 | ${ }^{2}$ Area H: ENGR 1000+, MATH/STAT 3000+, CPSC 3000+, MATH 2125, Science 1000+ |  |  |
| ENGR 5245U | minimum grade of C | 2 | ${ }^{3}$ ECON 2105 or ECON 2106 (recommended) |  |  |
| Area C1 | Humanities Elective ${ }^{5}$ | 3 | ${ }_{5}^{4}$ Area B1: COMM 1110 or FL 1001, 1002, 2001, 2002 |  |  |
|  | Credit Hours | 15 | ${ }_{6}^{5}$ Area C1: ENGL 2111, 2112; ITDS 1145,1155, 2125; PHIL 2010 |  |  |
| Spring <br> Area C2: ARTH 1100, 2125, 2126; ITDS 1145, MUSC 1100, THEA 1100 7 HIST 2111 or HIST 2112 |  |  |  |  |  |
| MATH 3175 | Introduction to Probability (minimum grade of C) | 3 | 8 World Culture: ANTH 1105, 1107, 2105, 2136; HIST 1111, 1112; ENGL 2136, GEOG 1101, ITDS 1156 |  |  |
| ENGR 3255 | Sensors and Actuators (minimum grade of C) | 3 | ${ }^{9}$ Area 1 Graduate electives: <br> - ENGR 6137 Dynamic Optimization |  |  |
| ENGR 3275 | Feedback Control Systems (minimum grade of C) | 3 | - ENGR 6145 Human-Robot Interactions <br> - ENGR 6148 Military Applications in Robotics |  |  |
| Area H | Elective (minimum grade of C) ${ }^{2}$ | 3 | - ENGR 6152 Computer Vision 2 |  |  |
| PEDS | Physical Education course 1*** | 1 | - ENGR 6162 Machine Intelligence and Synthesis |  |  |
| Area C2 | Fine Arts Elective ${ }^{6}$ | 3 | - ENGR 6167 Multi-Robot Systems |  |  |
|  | Credit Hours | 16 | - ENGR 6172 Multivariable Linear Controls |  |  |
| Fourth Year |  |  | - ENGR 6173 Nonlinear Controls |  |  |
| Fall |  |  | - ENGR 6178 Biomechanics |  |  |
| ENGR 4391 | Robotics Senior Design 1 (minimum grade of C) | 2 | - ENGR 6239 Embedded Systems Design <br> - ENGR 6555 Selected Topics in Robotics |  |  |
| ENGR 5161U | Elements of Machine Intelligence (minimum grade of C) | 3 | - any 5000+ CPSC/MATH class with advisor approval |  |  |
| ENGR 5176U | Kinematics and Dynamics (minimum grade of C) | 3 | BS/MS Robotics Engineering Non-Thesis Option 2 |  |  |
| ENGR 5236G | Microelectronic Circuits | 3 | Course | Title | Credit |
| Area E | American History ${ }^{7}$ | 3 |  |  |  |
|  | Credit Hours | 14 | First Year |  |  |
| Spring |  |  | Fall |  |  |
| ENGR 4392 | Robotics Senior Design 2 (minimum grade of C) | 2 | ENGL 1101 | English Composition I (minimum grade of C) | 3 |
| ENGR 5238G | Introduction to Embedded Systems | 3 | MATH 1131 | Calculus with Analytic Geometry I (minimum grade of C) | 4 |
| ENGR 5151U | Computer Vision 1 (minimum grade of C) | 3 |  |  |  |
| POLS 1101 | American Government | 3 | CHEM $1211 \begin{array}{ll}\text { Principles of Chemistry I (minimum grade } \\ \text { of C) }\end{array}$ |  |  |
| Area E | World Cultures Elective ${ }^{8}$ | 3 |  |  |  |  |  |
| Fifth Year | Credit Hours | 14 | CHEM 1211L | Principles of Chemistry I Lab (minimum grade of C) | 1 |
| Fall |  |  | ENGR 1701 | Introduction to Robotics (minimum grade of C) | 1 |
| Area 1 | Graduate Elective ${ }^{9}$ | 3 |  |  |  |
| Area 1 | Graduate Elective ${ }^{9}$ | 3 | ENGR 2255 | Engineering Graphics and Computer Aided Design (minimum grade of C ) |  |
| Area 1 | Graduate Elective ${ }^{9}$ | 3 | Area B2 | Institutional Options Elective ${ }^{1}$ | 1 |
| ENGR 6399 | Graduate Research Project | 3 |  | Credit Hours | 16 |
| Spring Credit Hours 12 |  |  | Spring Credit Hours 16 |  |  |
|  |  |  | ENGL 1102 | English Composition II (minimum grade of C) |  |
| Area 1 | Graduate Elective ${ }^{9}$ | 3 |  |  |  |  |
| Area 1 | Graduate Elective ${ }^{9}$ | 3 | MATH 1132 | Calculus with Analytic Geometry II (minimum grade of C ) |  |
| Area 2 | Graduate elective from Area 1 list ${ }^{9}$ | 3 |  |  |  |  |



- ENGR 6173 Nonlinear Controls
- ENGR 6178 Biomechanics
- ENGR 6239 Embedded Systems Design
- ENGR 6555 Selected Topics in Robotics
- any 5000+ CPSC/MATH class with advisor approval


## BS/MS Robotics Engineering Thesis Option

| Course | Title | Credit <br> Hours |
| :---: | :---: | :---: |
| First Year |  |  |
| Fall |  |  |
| ENGL 1101 | English Composition I (minimum grade of C) | 3 |
| MATH 1131 | Calculus with Analytic Geometry I (minimum grade of C) | 4 |
| CHEM 1211 | Principles of Chemistry I (minimum grade of C) | 3 |
| CHEM 1211L | Principles of Chemistry I Lab (minimum grade of C) | 1 |
| ENGR 1701 | Introduction to Robotics (minimum grade of C) | 1 |
| ENGR 2255 | Engineering Graphics and Computer Aided Design (minimum grade of C) | 3 |
| Area B2 | Institutional Options Elective ${ }^{1}$ | 1 |
|  | Credit Hours | 16 |
| Spring |  |  |
| ENGL 1102 | English Composition II (minimum grade of C) | 3 |
| MATH 1132 | Calculus with Analytic Geometry II (minimum grade of C ) | 4 |
| PHYS 2211 | Principles of Physics I (minimum grade of C) | 3 |
| PHYS 2311 | Principles of Physics I Lab (minimum grade of C) | 1 |
| Area H | Elective (minimum grade of C) ${ }^{2}$ | 3 |
| KINS 1106 or PHED 1205 | Lifetime Wellness or Concepts of Fitness | 2 |


| Second Year <br> Fall |  |  |
| :--- | :--- | ---: |
| MATH 2115 | Introduction to Linear Algebra (minimum <br> grade of C) | 3 |
| PHYS 2212 | Principles of Physics II (minimum grade of <br> C) | 3 |
| PHYS 2312 | Principles of Physics II Lab (minimum <br> grade of C) | 1 |
| ENGR 2115 | Statics (minimum grade of C) <br> ENGR 2221 | Computing for Engineers 1 (minimum <br> grade of C) |
| Area E | Behavioral Science Elective |  |

## Spring

MATH 3107 Differential Equations (minimum grade of C)

| ENGR 2206 | Digital Logic (minimum grade of C ) | 4 |
| :---: | :---: | :---: |
| ENGR 2125 | Dynamics of Rigid Bodies (minimum grade of C) | 3 |
| Area H | Elective (minimum grade of C) ${ }^{2}$ | 3 |
| Area B1 | Institutional Options Elective ${ }^{4}$ | 3 |
|  | Credit Hours | 16 |
| Third Year |  |  |
| Fall |  |  |
| MATH 2135 | Calculus with Analytic Geometry 3 (minimum grade of C ) | 4 |
| ENGR 3235 | Circuit Analysis (minimum grade of C) | 3 |
| ENGR 3236 | Introduction to Signal Processing (minimum grade of C ) | 3 |
| ENGR 5245U | minimum grade of $C$ | 2 |
| Area C1 | Humanities Elective ${ }^{5}$ | 3 |
|  | Credit Hours | 15 |
| Spring |  |  |
| MATH 3175 | Introduction to Probability (minimum grade of C) | 3 |
| ENGR 3255 | Sensors and Actuators (minimum grade of C) | 3 |
| ENGR 3275 | Feedback Control Systems (minimum grade of C) | 3 |
| Area H | Elective (minimum grade of C) ${ }^{2}$ | 3 |
| PEDS | Physical Education course 1*** | 1 |
| Area C2 | Fine Arts Elective ${ }^{6}$ | 3 |
|  | Credit Hours | 16 |
| Fourth Year |  |  |
| Fall |  |  |
| ENGR 4391 | Robotics Senior Design 1 (minimum grade of C) | 2 |
| ENGR 5161U | Elements of Machine Intelligence (minimum grade of C ) | 3 |
| ENGR 5176U | Kinematics and Dynamics (minimum grade of C) | 3 |
| ENGR 5236G | Microelectronic Circuits | 3 |
| Area E | American History ${ }^{7}$ | 3 |
|  | Credit Hours | 14 |
| Spring |  |  |
| ENGR 4392 | Robotics Senior Design 2 (minimum grade of C) | 2 |
| ENGR 5238G | Introduction to Embedded Systems | 3 |
| ENGR 5151U | Computer Vision 1 (minimum grade of C) | 3 |
| POLS 1101 | American Government | 3 |
| Area E | World Cultures Elective ${ }^{8}$ | 3 |
|  | Credit Hours | 14 |
| Fifth Year |  |  |
| Fall |  |  |
| Area 1 | Graduate Elective ${ }^{9}$ | 3 |
| Area 1 | Graduate Elective ${ }^{9}$ | 3 |
| Area 1 | Graduate Elective ${ }^{9}$ | 3 |
| ENGR 6999 | Thesis Research | 3 |
|  | Credit Hours | 12 |


| Spring |  |  |
| :--- | :--- | ---: |
| Area 1 | ${\text { Graduate Elective }{ }^{9}}^{9}$ | 3 |
| Area 1 | Graduate Elective $^{9}$ | 3 |
| ENGR 6999 | Thesis Research | 3 |
| ENGR 6999 | Thesis Research | 3 |
| ENGR 6000 | Thesis Defense | 0 |
|  | Credit Hours | $\mathbf{1 2}$ |
|  | Total Credit Hours | $\mathbf{1 4 7}$ |

## Footnotes

${ }^{1}$ Area B2: ITDS 1779 (2) or LEAD 1705 (2) or PERS 1506 (1; may be repeated with different topic) or PERS 1507 (2)
2 Area H: ENGR 1000+, MATH/STAT 3000+, CPSC 3000+, MATH 2125, Science 1000+
${ }^{3}$ ECON 2105 or ECON 2106 (recommended)
4 B1: COMM 1110 or FL 1001, 1002, 2001, 2002
5 Area C1: ENGL 2111, 2112; ITDS 1145, 1155, 2125; PHIL 2010
${ }^{6}$ Area C2: ARTH 1100, 2125, 2126; ITDS 1145, MUSC 1100, THEA 1100
7 HIST 2111 or HIST 2112
${ }^{8}$ World Culture: ANTH 1105, 1107, 2105, 2136; HIST 1111, 1112; ENGL 2136, GEOG 1101, ITDS 1156
9 Area 1 Graduate electives:

- ENGR 6137 Dynamic Optimization
- ENGR 6145 Human-Robot Interactions
- ENGR 6148 Military Applications in Robotics
- ENGR 6152 Computer Vision 2
- ENGR 6162 Machine Intelligence and Synthesis
- ENGR 6167 Multi-Robot Systems
- ENGR 6172 Multivariable Linear Controls
- ENGR 6173 Nonlinear Controls
- ENGR 6178 Biomechanics
- ENGR 6239 Embedded Systems Design
- ENGR 6555 Selected Topics in Robotics
- any 5000+ CPSC/MATH class with advisor approval


## Admission Requirements:

- Complete application for admission into this Combined BS/MS program.
- Attain junior standing (60 credits).
- Achieve minimum institutional GPA of 3.0 overall and 3.2 calculated on the following courses:
- MATH 1131/1132/2115/3107
- PHYS 2211/2311/2212/2312
- ENGR 1701/2115/2125/2206/2221/2255


## Academic Policies:

- No more than nine semester hours of graduate credit may be earned before completion of the baccalaureate degree.
- A maximum of two courses (not to exceed six semester credit hours) with a grade of "C" may apply to the master's degree.
- Students enrolled in the combined degree program must maintain a minimum graduate overall grade point average of 3.0 for the masters. The overall GPA of 3.0 also applies to undergraduate courses which
are required in the program. Students must be in Good Academic Standing to be eligible for graduation.

Combined degree students are expected to maintain Good Academic Standing as they progress
toward completing their programs. Students will be evaluated each term on the basis of the
overall GPA. The criteria for Good Academic Standing and Academic Probation are different for
undergraduate and graduate students.

## Eligibility to Remain in the Combined Program:

- Maintain a GPA of 3.0 or better.
- Complete all courses in Areas F, G, and the graduate program of study with a grade of not more than one D or F and not more than two Cs .

Any student who does not satisfy the above conditions will be moved from the Combined program back into the BS in Robotics Engineering program.

